

Performance Measures

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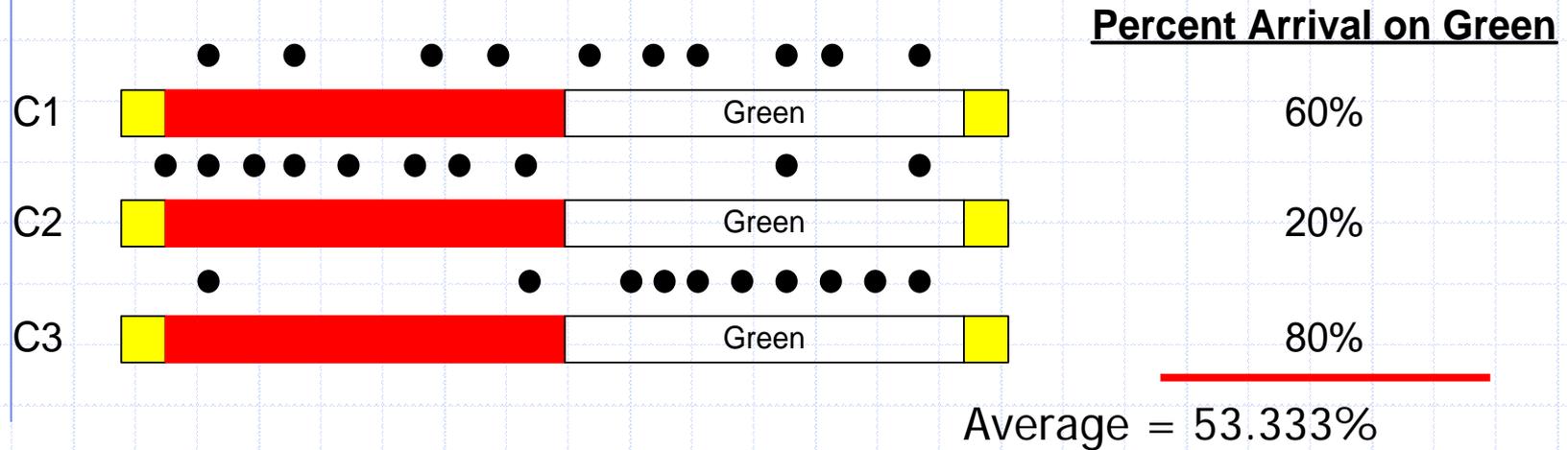
Green Occupancy Ratio (GOR) and Arrival Type (AT)

- ◆ Data requirements
- ◆ Theory
- ◆ Performance data
 - Signal Performance
 - Progression Performance

Data Requirement

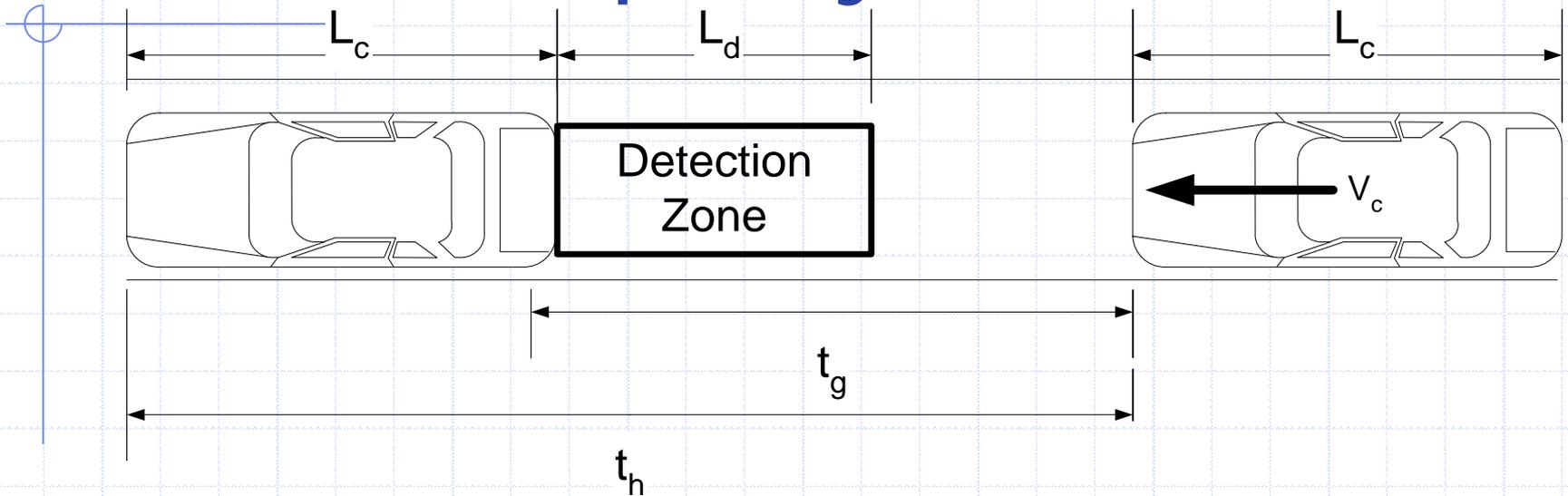
- ◆ Event based data (0.1 second resolution)
 - Controller or other data collection device
- ◆ Phase and detector status
 - GOR: Phase, stopbar presence
 - AT: Phase, advance count (presence can be used)

Why event based data?



- ◆ Aggregation removes fidelity
- ◆ Aggregation typically based upon minutes
 - Does not align with cycles

Green Occupancy Ratio



$$O_g = \sum_{i=1}^n \frac{(L_{ci} + L_d)}{V_{ci}}$$

$$GOR = \frac{O_g}{g_i}$$

where

- O_g = Occupancy of a green interval i
- L_d = Length of detection zone
- L_c = Length of vehicle
- V_c = Velocity of vehicle
- t_g = time gap between vehicles
- t_h = time headway between vehicles

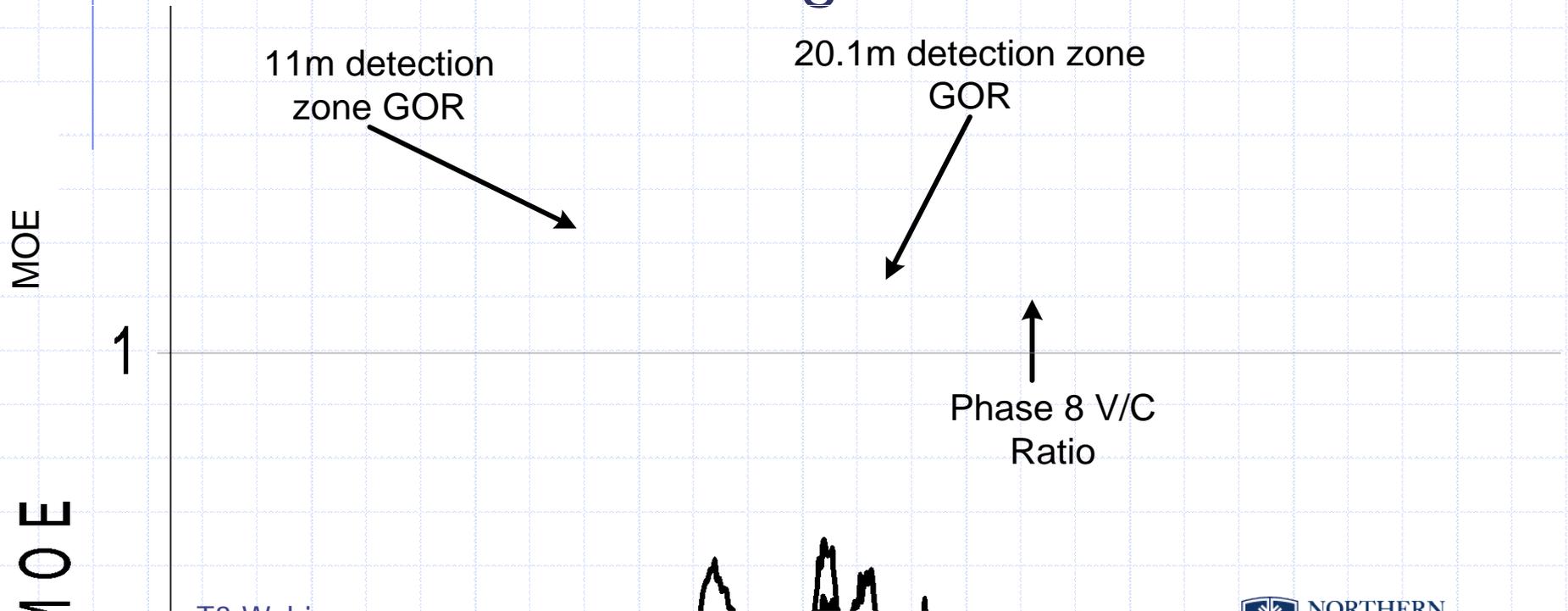
Green Occupancy Ratio

◆ Measure of signal performance

- Higher volume, less detector off time, higher metric value
- Metric value dependent on vehicle speed and detection zone length
 - ◆ Lower speeds => Higher metric value
 - ◆ Shorter detection zone => Lower metric value

Green Occupancy Ratio

◆ Comparison to V/C, with different detection zone lengths



Arrival Type

- ◆ Measure of progression performance
- ◆ Well known Highway Capacity Manual concept
 - Value has impact on delay calculation
 - Value can be developed
 - ◆ Qualitatively
 - ◆ Quantitatively

Arrival Type - Qualitative

EXHIBIT 10-18. PROGRESSION QUALITY AND ARRIVAL TYPE

Progression Quality	Arrival Type	Conditions Under Which Arrival Type Is Likely To Occur
Very poor	1	Occurs for coordinated operation on two-way street where one direction of travel does not receive good progression. Signals are spaced less than 1,600 ft apart.
Unfavorable	2	A less extreme version of Arrival Type 1. Signals spaced at or more than 1,600 ft but less than 3,200 ft apart.
Random arrivals	3	Isolated signals spaced at or more than 3,200 ft apart (whether or not coordinated).
Favorable	4	Occurs for coordinated operation, often only in one direction on a two-way street. Signals are typically between 1,600 ft and 3,200 ft apart.
Highly favorable	5	Occurs for coordinated operation. More likely to occur with signals less than 1,600 ft apart.
Exceptional	6	Typical of one-way streets in dense networks and central business districts. Signal spacing is typically under 800 ft.

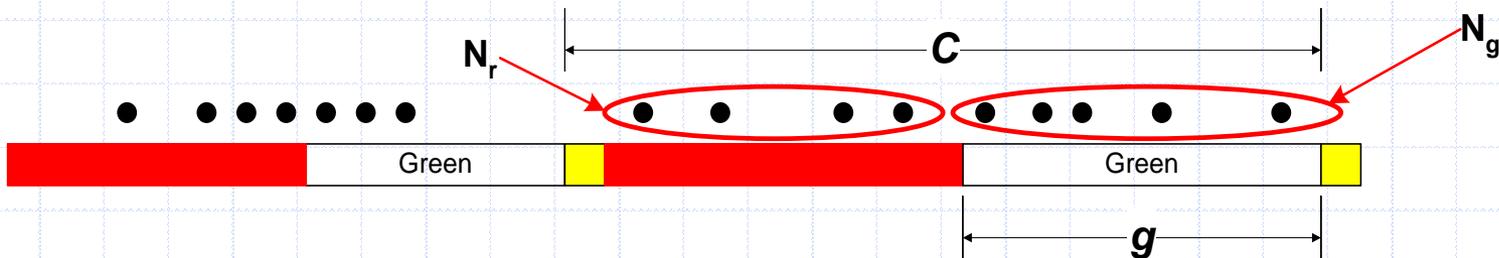
Exhibit 10-18, HCM 2000

Arrival Type - Quantitative

Arrival Type	Range of Platoon Ratio (R_p)	Default Value (R_p)	Progression Quality
1	≤ 0.50	0.333	Very poor
2	$> 0.50 - 0.85$	0.667	Unfavorable
3	$> 0.85 - 1.15$	1.000	Random arrivals
4	$> 1.15 - 1.50$	1.333	Favorable
5	$> 1.50 - 2.00$	1.667	Highly favorable
6	> 2.00	2.000	Exceptional

$$R_p = P \left(\frac{C}{g} \right)$$

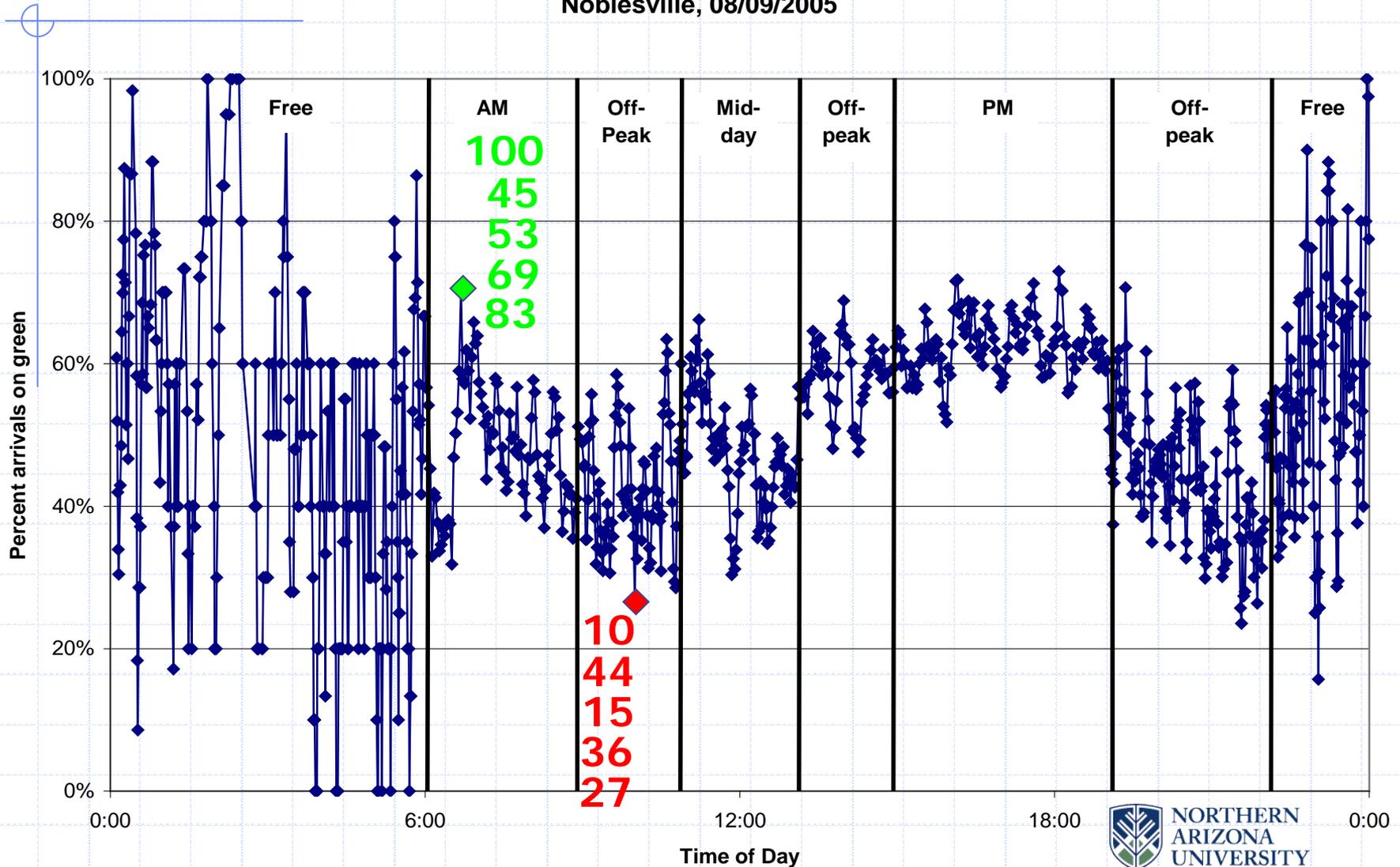
R_p = Platoon Ratio
 P = Percent of Vehicle Arriving on Green
 C = Cycle Length
 G = Length of green interval



Arrival Type Sample Data

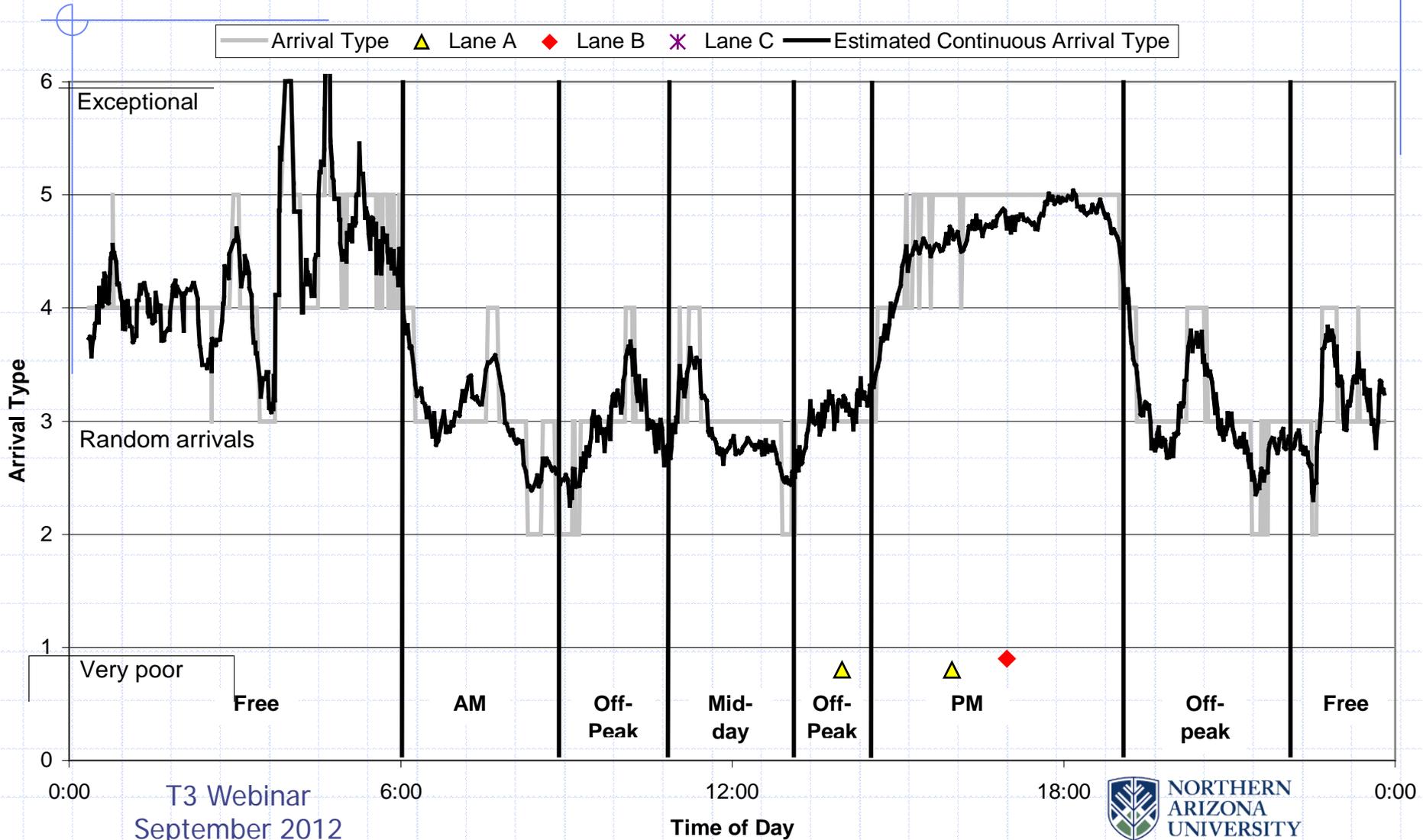
$$R_p = P\left(\frac{C}{g}\right)$$

Percent arrivals on green (5 cycle moving average), Northbound approach Phase 2, Noblesville, 08/09/2005



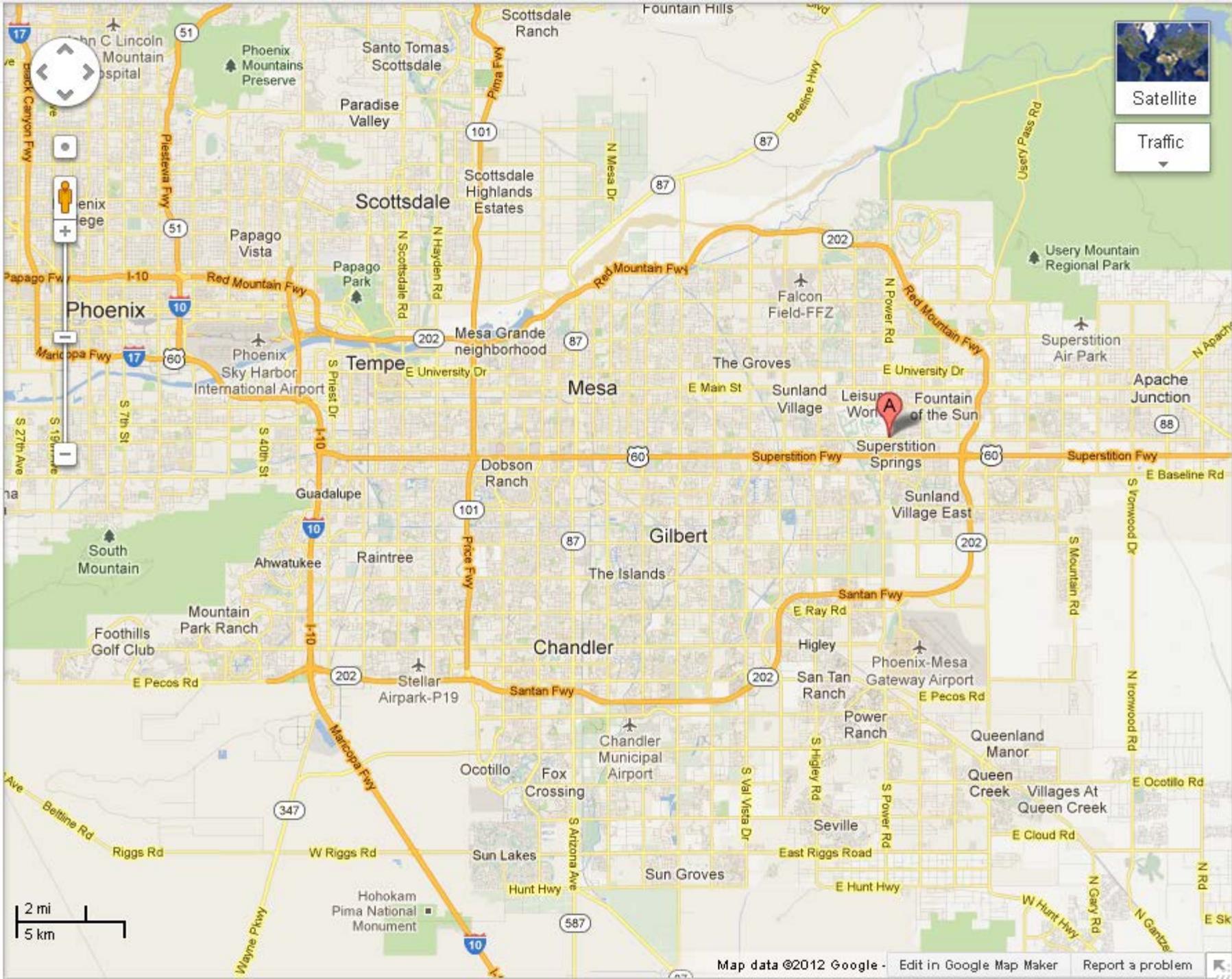
Arrival Type Sample Data

$$R_p = P\left(\frac{C}{g}\right)$$

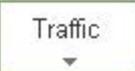


City of Mesa test intersection

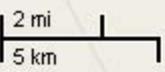
- ◆ E. Southern Rd & S. Power Ave located on the east side of Mesa
- ◆ Geography
 - Adjacent to Shopping Mall and Retirement Community
 - 1/2 mi north of US 60
 - Wide Streets
- ◆ Adaptive control system location



Satellite



Traffic



Data collection instrumentation plan

E. Southern Ave. & S. Power Rd, Mesa AZ



- Legend
-  Video / Data Collection Camera
 -  6x6 Inductive Loop Detector
 -  Camera Number

Notes

- This plan is not drawn to scale.
- 6x6 loops are located about 400' back from the stop bar in each through lane, each on a separate channel.
- 6x6 loops are located at the stopbar for each individual lane, each on its own channel, with the exception of loops in dual left turn bays, which share a channel.
- Cameras 1-4 are mounted on existing mast arms, located transversely at a point between the oncoming through and left turn lanes.

What do I need?

- ◆ Event based data logger
 - Adaptive system
 - Available on certain:
 - ◆ Traffic controllers
 - ◆ Video detection devices
 - Standalone device
- ◆ Access to detector and phase state changes on 0.1s resolution